

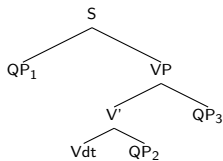
Scope ambiguities, continuations and strengths

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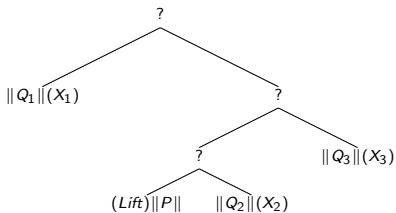
University of Warsaw

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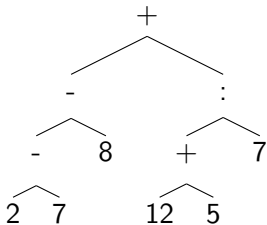
Some teacher gave every student most books (6-way ambiguous)



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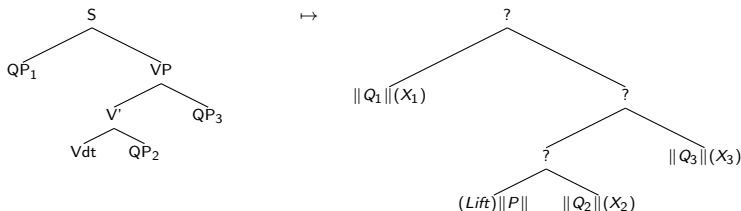


$$((2 - 7) - 8) + ((12 + 5) : 7)$$



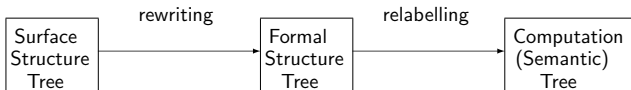
Introduction

Some teacher gave every student most books (6-way ambiguous)



Challenges

- calculate the truth-value in each of sentence's readings
- leaving the shape of the syntactic tree as intact as possible
- keep the operations as simple as possible



Mainstream Scope Assignment Strategies

Strategy	A <i>Movement Strategy</i> (May 77)	B <i>Polyadic Approach</i> (May 85)	C <i>Continuation-based Approach</i> (Barker 2002)
<i>Rewrite rules</i>	QR	QR, Rotation	No rewrite rules (in situ)
<i>Relabelling inner nodes (operations)</i>	mos	mos pile' up	CPS
<i>Relabelling leaves (semantic values)</i>	<i>Predicate</i> \mapsto <i>relation</i> QP \mapsto C-comp.	<i>Predicate</i> \mapsto <i>relation</i> QP \mapsto C-comp.	<i>Predicate</i> \mapsto <i>continuiuzed relation</i> QP \mapsto C-comp.

Strategy	A <i>Movement Strategy (May 77)</i>	B <i>Polyadic Approach (May 85)</i>	C <i>Cont-based Approach (Barker 02)</i>	D Strat C <i>& new shuffle operations</i>
<i>6 readings</i>	✓	✓	-	✓
<i>in situ</i>	-	-	✓	✓
<i>simple operations</i>	✓	✓?	✓??	???

- 1 Monads
 - 1 definition
 - 2 strength(s) and derived operations
- 2 Continuation monad
 - 1 definition
 - 2 strength(s) and derived operations
- 3 Scope-Assignment Strategies
 - 1 Strategy A: traditional movement strategy (May 77, Montague 74);
 - 2 Strategy B: polyadic approach (May 85, Keenan 87, Zawadowski 89);
 - 3 Strategy C: continuation-based (in situ) approach (Barker 2002).
- 4 Empirically adequate in situ Strategy D: **shuffle**-operations.

A **monad** on *Set* is a triple (+ conditions ...):
***T*-computations** (endofunctor)

$$\begin{array}{ccc} \text{Set} & \xrightarrow{T} & \text{Set} \\ \\ X & \xrightarrow{\quad} & T(X) \\ f \downarrow & \dashv\!\!\dashv\!\!\dashrightarrow & \downarrow T(f) \\ Y & & T(Y) \end{array}$$

unit (return) (natural transformation)

$$\begin{aligned} \eta &: 1_{\text{Set}} \longrightarrow T \\ \eta_X &: X \longrightarrow T(X) \end{aligned}$$

lifts elements of X as T -computations.

multiplication (natural transformation)

$$\begin{aligned} \mu &: T^2 \longrightarrow T \\ \mu_X &: T^2(X) = T(T(X)) \longrightarrow T(X) \end{aligned}$$

flattens T -computations on T -computations to T -computations.

Let (T, η, μ) be a monad on Set .

The **left (right) strength** is a natural transformation with components

$$\mathbf{st}^l_{X,Y} : T(X) \times Y \longrightarrow T(X \times Y)$$

$$(\mathbf{st}^r_{X,Y} : X \times T(Y) \longrightarrow T(X \times Y))$$

for sets X and Y (plus some conditions).

Strengths allow to lift pairs of T -computations to T -computations on products!

For any sets X and Y , the *left (right) pile up* **pile'up** $^l_{X,Y}$ (**pile'up** $^r_{X,Y}$) is defined as the composition

$$\begin{array}{ccc}
 T(X) \times T(Y) & \xrightarrow{\text{pile'up}^l_{X,Y}} & T(X \times Y) \\
 \text{st}^l_{X,T(Y)} \downarrow & & \uparrow \mu_{X \times Y} \\
 T(X \times T(Y)) & \xrightarrow{T(\text{st}^r_{X,Y})} & T^2(X \times Y)
 \end{array}$$

$$\begin{array}{ccc}
 T(X) \times T(Y) & \xrightarrow{\text{pile'up}^r_{X,Y}} & T(X \times Y) \\
 \text{st}^r_{T(X),Y} \downarrow & & \uparrow \mu_{X \times Y} \\
 T(T(X) \times Y) & \xrightarrow{T(\text{st}^l_{X,Y})} & T^2(X \times Y)
 \end{array}$$

There are two (binary) T -transformations, right and left. For a function $f : X \times Y \rightarrow T(Z)$, the left and right T -transform is defined as the composition

$$\begin{array}{ccc}
 T(X) \times T(Y) & \xrightarrow{\mathbf{TR}^l, T_{X,Y}(f)} & T(Z) \\
 \text{pile'up}^l \downarrow & & \uparrow \mu_Z \\
 T(X \times Y) & \xrightarrow{T(f)} & T^2(Z)
 \end{array}$$

$$\begin{array}{ccc}
 T(X) \times T(Y) & \xrightarrow{\mathbf{TR}^r, T_{X,Y}(f)} & T(Z) \\
 \text{pile'up}^r \downarrow & & \uparrow \mu_Z \\
 T(X \times Y) & \xrightarrow{T(f)} & T^2(Z)
 \end{array}$$

Continuation monad \mathcal{C} (endofunctor)

- $\mathbf{t} = \{0, 1\}$, $\mathcal{P}(X) = X \Rightarrow \mathbf{t}$ - powerset of X ;
- function $f : X \rightarrow Y$ induces an inverse image function between powersets

$$\mathcal{P}(f) = f^{-1} : \mathcal{P}(Y) \rightarrow \mathcal{P}(X)$$

$$h \mapsto h \circ f, \quad \mathcal{P}(f) = \lambda h : \mathcal{P}(Y). \lambda x : X. h(f\ x)$$

- taking again an inverse image function

$$\mathcal{C}(f) = \mathcal{P}(f^{-1}) : \mathcal{C}(X) = \mathcal{P}^2(X) \rightarrow \mathcal{P}^2(Y) = \mathcal{C}(Y)$$

$$Q \mapsto Q \circ f^{-1}, \quad \mathcal{C}(f)(Q) = \lambda h : \mathcal{P}(Y). Q(\lambda x : X. h(f\ x))$$

for $Q \in \mathcal{C}(X)$.

Continuation Monad

notion of computation

Now we can look at the notion of computation related to \mathcal{C}

$$f : X \longrightarrow \mathcal{C}(Y) = \mathcal{P}(Y) \Rightarrow \mathbf{t}$$

By exponential adjunction (uncurrying) it corresponds to a function

$$f' : \mathcal{P}(Y) \times X \longrightarrow \mathbf{t}$$

and again by exponential adjunction (currying) it corresponds to a function

$$f'' : \mathcal{P}(Y) \longrightarrow \mathcal{P}(X)$$

$$\begin{array}{ccccc} & & & & f(c) \\ & & & & \downarrow \\ & \lrcorner & & & \downarrow \\ X & \xrightarrow{f?} & Y & \xrightarrow{c} & \mathbf{t} \end{array}$$

Continuation monad \mathcal{C} (natural transformations)

The **unit**

$$\eta_X : X \rightarrow \mathcal{C}(X)$$

is given by

$$\eta_X(x) = \lambda h:\mathcal{P}(X).h(x)$$

for $x \in X$.

The **multiplication**

$$\mu_X : \mathcal{C}^2(X) \longrightarrow \mathcal{C}(X)$$

is given by

$$\mu_X(\mathcal{F})(h) = \mathcal{F}(\lambda D:\mathcal{C}(X).D(h))$$

for $\mathcal{F} \in \mathcal{C}^2(X)$ and $h \in \mathcal{P}(X)$.

For the continuation monad, the **left strength** is

$$\mathbf{st}^l : \mathcal{C}(X) \times Y \longrightarrow \mathcal{C}(X \times Y)$$

$$\mathbf{st}^l(N, y) = \lambda c : \mathcal{P}(X \times Y). N(\lambda x : X. c(x, y))$$

for $N \in \mathcal{C}(X)$ and $y \in Y$.

and the **right strength** is

$$\mathbf{st}^r : X \times \mathcal{C}(Y) \longrightarrow \mathcal{C}(X \times Y)$$

$$\mathbf{st}^r(x, M) = \lambda c : \mathcal{P}(X \times Y). M(\lambda y : Y. c(x, y))$$

for $x \in X$ and $M \in \mathcal{C}(Y)$.

Continuation monad

pile'up-operations

For the continuation monad, both **pile'up**-operations can be defined by lambda terms as follows. For $M \in \mathcal{C}(X)$ and $N \in \mathcal{C}(Y)$ we have

$$\mathbf{pile'up}^l : \mathcal{C}(X) \times \mathcal{C}(Y) \rightarrow \mathcal{C}(X \times Y)$$

$$\mathbf{pile'up}^l(M, N) = \lambda c : \mathcal{P}(X \times Y). M(\lambda x : X. N(\lambda y : Y. c(x, y)))$$

$$\mathbf{pile'up}^r : \mathcal{C}(X) \times \mathcal{C}(Y) \rightarrow \mathcal{C}(X \times Y).$$

$$\mathbf{pile'up}^r(M, N) = \lambda c : \mathcal{P}(X \times Y). N(\lambda y : Y. M(\lambda x : X. c(x, y))).$$

Thus in the case of the continuation monad ‘piling up’ computations one on top of the other is nothing but putting (interpretations of) quantifiers in order, either first before the second or the second before the first.

Transforms for monad \mathcal{C} are called **CPS**-transforms.

For $f : X \times Y \rightarrow Z$ we have

$$\mathbf{CPS}'(f) = \mathcal{C}(f) \circ \mathbf{pile}'\mathbf{up}'_{X,Y} : \mathcal{C}(X) \times \mathcal{C}(Y) \longrightarrow \mathcal{C}(Z)$$

given for $M \in \mathcal{C}(X)$ and $N \in \mathcal{C}(Y)$ by

$$\mathbf{CPS}'(f)(M, N) = \lambda h : \mathcal{P}(Z). M(\lambda x : X. N(\lambda y : Y. h(f(x, y))))).$$

Right version is similar.

Continuation monad

CPS-transforms of applications

The most popular **CPS**-transforms are those for the evaluation (application) $ev : X \times (X \Rightarrow Y) \rightarrow Y$

$$\mathbf{CPS}'(ev) = \mathcal{C}(ev) \circ \mathbf{pile}'\mathbf{up}'_{X, X \Rightarrow Y} : \mathcal{C}(X) \times \mathcal{C}(X \Rightarrow Y) \longrightarrow \mathcal{C}(Y)$$

given for $M \in \mathcal{C}(X)$ and $N \in \mathcal{C}(X \Rightarrow Y)$ by

$$\mathbf{CPS}'(ev)(M, N) = \lambda h : \mathcal{P}(Y). M(\lambda x : X. N(\lambda g : X \Rightarrow Y. h(g x))).$$

Right version is similar.

Continuation monad

Other morphisms having useful transforms

Left evaluations

$$\mathbf{eps}'_X = \lambda h:\mathcal{P}(X).\lambda x:X.h(x) : \mathcal{P}(X) \times X \rightarrow \mathbf{t};$$

$$\mathbf{eps}'_Y^X = \mathbf{eps}'_Y = \lambda c:\mathcal{P}(X \times Y).\lambda y:Y.\lambda x:X.c(x, y) : \mathcal{P}(X \times Y) \times Y \rightarrow \mathcal{P}(X);$$

and right evaluations ...

Left **mos'**es

$$\mathbf{mos}'_X = \lambda Q:\mathcal{C}(X).\lambda c:\mathcal{P}(X).Q(c) : \mathcal{C}(X) \times \mathcal{P}(X) \rightarrow \mathbf{t};$$

$$\mathbf{mos}'_Y = \lambda Q:\mathcal{C}(Y).\lambda c:\mathcal{P}(X \times Y).\lambda x:X.Q(\lambda y:Y.c(x, y)) : \mathcal{C}(Y) \times \mathcal{P}(X \times Y) \rightarrow \mathcal{P}(X);$$

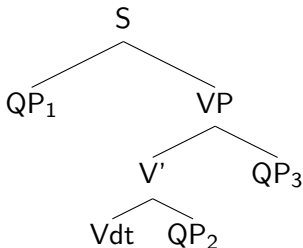
and right **mos'**es...

Scope assignment strategies

Example: sentence with 3 QPs

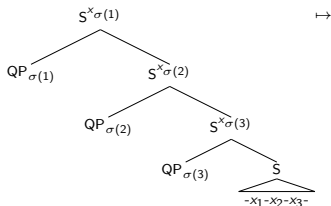
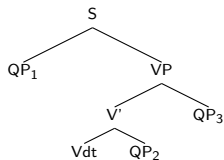
Sentence with three QPs, e.g.

Some teacher gave every student most books.

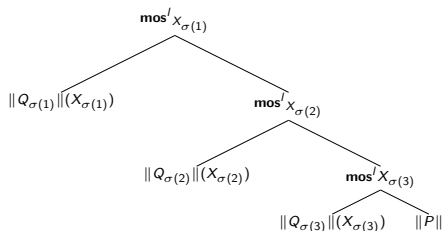


Scope assignment strategies

Strategy A



\mapsto



Scope assignment strategies

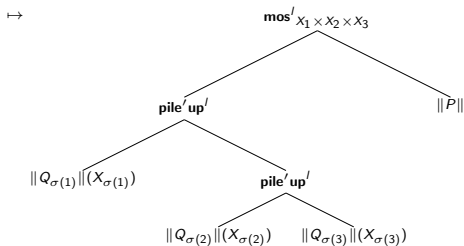
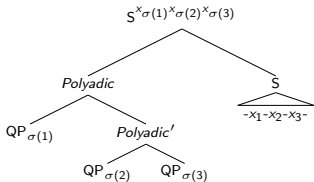
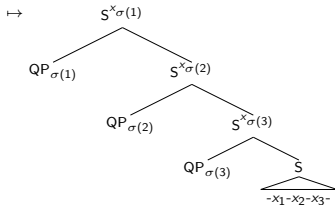
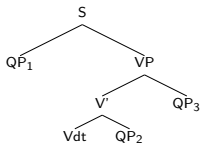
Strategy A

The Computation Tree gives rise to the following general map, with $\sigma \in S_3$

$$\begin{array}{c} \mathcal{C}(X_1) \times \mathcal{P}(X_1 \times X_2 \times X_3) \times \mathcal{C}(X_2) \times \mathcal{C}(X_3) \xrightarrow{\bar{\pi}_{\sigma(i)}} \mathcal{C}(X_{\sigma(i)}) \\ \text{strat}_A^{3,\sigma} : \downarrow \langle \bar{\pi}_{\sigma(1)}, \bar{\pi}_{\sigma(2)}, \bar{\pi}_{\sigma(3)}, \pi_2 \rangle \\ \mathcal{C}(X_{\sigma(1)}) \times \mathcal{C}(X_{\sigma(2)}) \times \mathcal{C}(X_{\sigma(3)}) \times \mathcal{P}(X_1 \times X_2 \times X_3) \\ \downarrow 1 \times 1 \times \mathbf{mos}'_{X_{\sigma(3)}} \\ \mathcal{C}(X_{\sigma(1)}) \times \mathcal{C}(X_{\sigma(2)}) \times \mathcal{P}(\dots \times \widehat{X_{\sigma(3)}} \times \dots) \\ \downarrow 1 \times \mathbf{mos}'_{X_{\sigma(2)}} \\ \mathcal{C}(X_{\sigma(1)}) \times \mathcal{P}(X_{\sigma(1)}) \\ \downarrow \mathbf{mos}'_{X_{\sigma(1)}} \\ 2 \end{array}$$

Scope assignment strategies

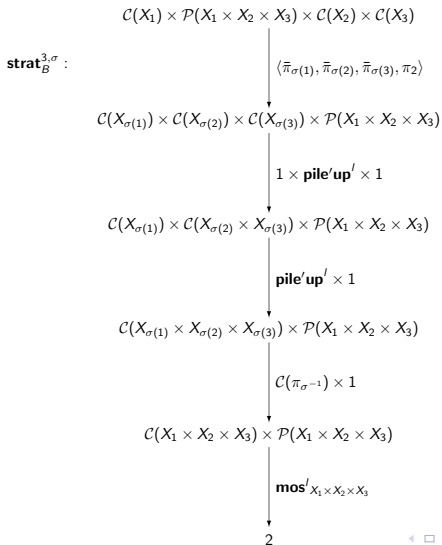
Strategy B



Scope assignment strategies

Strategy B

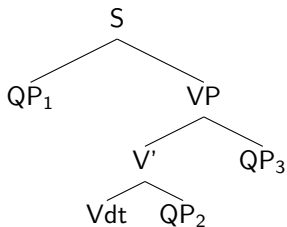
The Computation Tree gives rise to the following general map



Scope assignment strategies

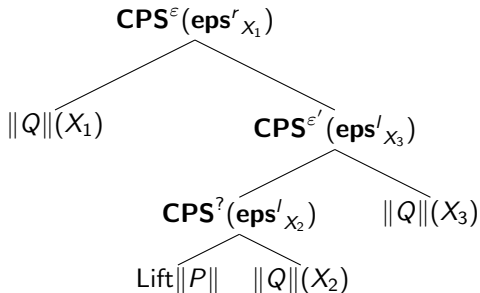
Strategy C

Surface Structure Tree



↪

Computation Tree



Scope assignment strategies

Strategy C

The Computation Tree gives rise to the following general map

$$\begin{array}{c} \text{strat}_C^{3, \epsilon', \epsilon} : \\ \begin{array}{c} \mathcal{C}(X_1) \times \mathcal{P}(X_1 \times X_2 \times X_3) \times \mathcal{C}(X_2) \times \mathcal{C}(X_3) \\ \downarrow 1 \times \eta_{\mathcal{P}(X_1 \times X_2 \times X_3)} \times 1 \times 1 \\ \mathcal{C}(X_1) \times \mathcal{CP}(X_1 \times X_2 \times X_3) \times \mathcal{C}(X_2) \times \mathcal{C}(X_3) \\ \downarrow 1 \times \mathbf{CPS}^2(\text{eps}'_{X_2}) \times 1 \\ \mathcal{C}(X_1) \times \mathcal{CP}(X_1 \times X_3) \times \mathcal{C}(X_3) \\ \downarrow 1 \times \mathbf{CPS}^{\epsilon'}(\text{eps}'_{X_3}) \\ \mathcal{C}(X_1) \times \mathcal{CP}(X_1) \\ \downarrow \mathbf{CPS}^{\epsilon}(\text{eps}^r_{X_1}) \\ \mathcal{C}(2) \end{array} \end{array} \xrightarrow{\text{evid}_2} 2$$

Scope assignment strategies

Strategy C

- Strategy C provides a uniform non-movement (in situ) analysis of quantifiers.
- However, it cannot be straightforwardly extended to account for sentences involving 3 QPs - as proved in our ArXiv paper, it only provides **4 out of 6 readings** accounted for by the two other strategies.
- We can augment Strategy C to obtain the missing readings. To this end, we use **CPS-** (and **pile'up-**) operations to define two new operations: **shuf'** and **shuf^r**.

To get the first missing reading

$$QP_2 > QP_1 > QP_3,$$

we define a new operation

$$\mathbf{shuf}' : \mathcal{CP}(X_1 \times X_3) \times \mathcal{C}(X_3) \rightarrow \mathcal{PC}(X_1)$$

$$\mathbf{shuf}'(S_2, S_3) =$$

$$= \lambda S_1 : \mathcal{C}(X_1). \mathbf{CPS}'(\mathbf{eps}'_{X_3})(\mathbf{CPS}'(\mathbf{eps}'_{X_1})(S_2, S_1), S_3)(id_t) =$$

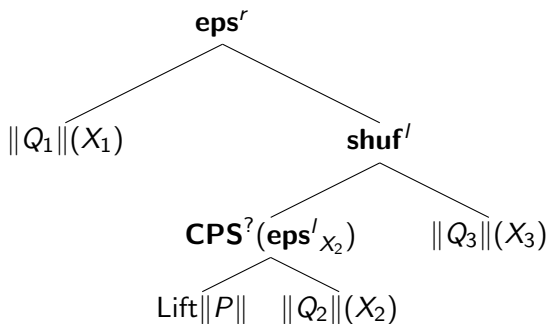
$$= \lambda S_1 : \mathcal{C}(X_1). \mathbf{CPS}'(\mathbf{eps}'_{X_1 \times X_3})(S_2, \mathbf{pile}'\mathbf{up}'(S_1, S_3))(id_t)$$

for $S_2 \in \mathcal{CP}(X_1 \times X_3)$ and $S_3 \in \mathcal{C}(X_3)$.

Scope assignment strategies

Strategy D

Computation Tree



To get the second of the two missing readings

$$QP_3 > QP_1 > QP_2,$$

we define a new operation

$$\mathbf{shuf}^r : \mathcal{CP}(X_1 \times X_3) \times \mathcal{C}(X_3) \rightarrow \mathcal{PC}(X_1)$$

$$\mathbf{shuf}^r(S_2, S_3) =$$

$$= \lambda S_1 : \mathcal{C}(X_1). \mathbf{CPS}'(\mathbf{eps}^r_{X_3})(S_3, \mathbf{CPS}'(\mathbf{eps}^r_{X_1})(S_1, S_2))(id_t) =$$

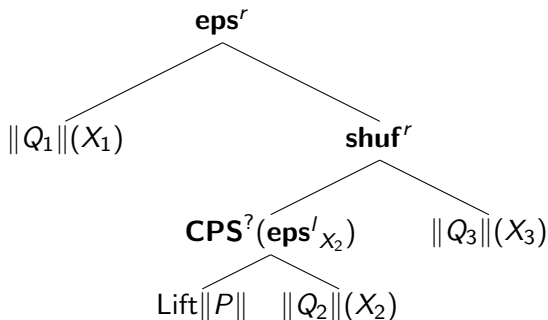
$$= \lambda S_1 : \mathcal{C}(X_1). \mathbf{CPS}'(\mathbf{eps}^r_{X_1 \times X_3})(\mathbf{pile}'\mathbf{up}'(S_3, S_1), S_2)(id_t)$$

for $S_2 \in \mathcal{CP}(X_1 \times X_3)$ and $S_3 \in \mathcal{C}(X_3)$.

Scope assignment strategies

Strategy D

Computation Tree



Thank You for Your Attention!